

# Leaflet

# **Inland AIS**

# Leaflet Edition 2011

# Inland AIS

#### Contents

1.	Principles	5
1.1	Scope	5
1.2	Purpose of Inland AIS	5
1.3	Compatibility with maritime AIS	5
1.4	Characteristics of AIS	5
1.5	System-related performance limits for AIS	6
2.	International standardisation of Inland AIS	6
2.1	Purpose	6
2.2	Legal bases	7
2.3	Structure of the Standard (of the technical specifications) for Vessel Tracking	
	and Tracing in Inland Navigation	7
2.4	Current editions	8
2.5	Type approval of Inland AIS devices	8
3.	RIS fields of interest covered	8
4.	Functioning of Inland AIS	10
5	Operating modes of AIS	11
6	AIS devices	11
7.	Information transmitted by Inland AIS	11
7.1	Static ship information	12
7.2	Dynamic ship information	13
7.3	Voyage-related ship information	13
7.4	Traffic management information	14
7.5	ETA at lock/bridge/terminal	14
7.6	RTA at lock/bridge/terminal	14
7.7	Number of persons on board	14
7.8	Signal status	14
7.9	EMMA weather warnings	15
7.10	Water level reports	15
7.11	Safety-related messages	15

8.	Reporting interval for information transmission	15
9.	On-board operation of Inland AIS devices	16
10.	Display of information transmitted by Inland AIS	17
11.	Installation of Inland AIS devices on board	18
12.	Status of Inland AIS implementation in European countries	19
13.	Contacts	20
14.	Abbreviations	21

# 1. Principles

#### 1.1 Scope

The Automatic Identification System (AIS) is a ship borne radio data system, exchanging static, dynamic and voyage related vessel data between equipped vessels and between equipped vessels and shore stations. Ship borne AIS stations broadcast the vessel's identity, position and other data in regular intervals. By receiving these transmissions, ship borne or shore based AIS stations within the radio range can automatically locate, identify and track AIS equipped vessels on an appropriate display like radar or Inland ECDIS.

AIS is widely used in maritime navigation, There are numerous AIS devices such as Class A mobile stations, mandatory for sea going vessels falling under the IMO SOLAS, Class B mobile stations with limited functionality to be used by e.g. pleasure crafts, and base stations for the use on shore.

This leaflet introduces the concept of Inland AIS, a special development within the AIS to serve the specific requirements of professional inland navigation.

#### 1.2 Purpose of Inland AIS

Inland AIS (AIS stands for "Automatic Identification System") is a standardised procedure for the automatic exchange of nautical data between ships and between ships and shore installations.

As an instrument for the tracking and tracing of inland navigation vessels it is one of the four key-technologies for "River Information Services" (RIS) for inland navigation and its purpose is to improve safety and efficiency in the sector.

It supports onboard navigation, shore-based traffic monitoring as part of Vessel Traffic Services (VTS) and other tasks such as calamity abatement.

#### 1.3 Compatibility with maritime AIS

The information content of Inland AIS basically tallies with that of maritime AIS, while providing additional information specific to inland waterways. In view of their shared information content, Inland AIS and maritime AIS are compatible. All data transmitted can be received by both maritime and Inland AIS devices to be visually displayed and analysed. However the specifically Inland AIS information is only transmitted and assessed by Inland AIS devices.

#### 1.4 Characteristics of AIS

AIS is a cooperative procedure, therefore all those wishing to use and participate in the system must be equipped with an AIS device.

Vessels fitted with AIS transmit and receive information on an automatic and periodical basis from other ships equipped with AIS. This information regards the vessel and its current nautical data:

- Identity of the ship,
- Its exact position,
- Its course and speed,
- Other ship-specific data.

The data provided by AIS can be visualised in various ways. The most efficient way of going about this is to display the identity of the vessel and geo-referenced data such as that on its position and movements on a chart, and compile static data in alphanumerical form in tables.

AIS shore stations within VHF radio range can also receive these data and in turn broadcast navigation-related information to vessels.

AIS is an additional source for navigation-related information. AIS does not replace navigationrelated services such as tracking by radar and VTS, but in fact supports them. The strength of AIS lies in the detection and tracking of those craft fitted with it. AIS and radar complement one another due to their different characteristics.

#### 1.5 System-related performance limits of AIS

The following points are to be considered when using information conveyed by AIS:

- Not all vessels are equipped with AIS. Users, particularly the shipmaster, should always bear in mind that other vessels may <u>not</u> be fitted with AIS, or that an AIS device installed on another ship might transmit incomplete or erroneous information.
- Users should ensure they are in a position to construe the data received correctly.
- AIS is purely an additional source of information. It in no way replaces navigation aids such as radar, but is intended to support them.

# 2. International standardisation of Inland AIS

#### 2.1 Purpose

Both standards and harmonised procedures are required to ensure the interoperability of devices from various manufacturers, whilst guaranteeing that they operate safely.

As part of the standardisation of tracking and tracing for inland navigation, the Inland AIS Standard and the Test Standard for Inland AIS were developed.

The Inland AIS Standard and the Test Standard for Inland AIS define:

- Functional requirements for Inland AIS devices,
- Technical requirements for Inland AIS devices,
- Specification of AIS messages for the exchange of messages between Inland AIS devices via radio,
- Specification of AIS data sets for data exchange between Inland AIS devices and connected applications.

The European Expert Group "Vessel Tracking and Tracing on Inland Waterways" drew up the Inland AIS Standard and the Test Standard for Inland AIS and will, if need be, make proposals for their further development

#### 2.2 Legal bases

Resolution of the Central Commission for the Navigation of the Rhine (CCNR) of 31 May 2006: "Vessel Tracking and Tracing Standard for Inland Navigation (VTT Standard 2006)" (Protocol 2006-I-21)

Decision of the Police Committee, Central Commission for the Navigation of the Rhine (CCNR) of 10 October 2007. "Vessel Tracking and Tracing Standard for Inland Navigation (VTT Standard, Edition 1.01)" (Protocol 2007-II-31)

Commission Regulation (EC) No 415/2007 of 13 March 2007 concerning the technical specifications for vessel tracking and tracing systems referred to in Article 5 of Directive 2005/44/EC of the European Parliament and of the Council on harmonised river information services (RIS) on inland waterways in the Community [revision expected for second half of 2011]

Resolution of the Central Commission for the Navigation of the Rhine (CCNR) of 31 May 2007: "Vessel Tracking and Tracing Standard for Inland Navigation – Type approval, installation and operation of Inland AIS devices on inland navigation vessels" (Protocol 2007-I-15)

Resolution of the Central Commission for the Navigation of the Rhine (CCNR) of 6 December 2007: "Vessel Tracking and Tracing Standard for Inland Navigation – Type approval, installation and operation of Inland AIS devices on inland navigation vessels" (Protocol 2007-II-24)

Decision of the Police Committee, Central Commission for the Navigation of the Rhine (CCNR) of 22 October 2008. "Test Standard for Inland AIS, Edition 1.01)" (Protocol 2008-II-20)

Police Regulation for Rhine Navigation, § 4.07

Rhine Vessel Inspection Regulation, § 7.06 Nr. 3

# 2.3 Structure of the Standard (of the technical specifications) for Vessel Tracking and Tracing in Inland Navigation

The Standard for Vessel Tracking and Tracing in Inland Navigation comprises the following sections:

- The usage of vessel tracking and tracing in inland navigation (functional description)
- Inland AIS Standard (including Inland AIS radio messages (VDL Messages, VHF data link))
- Definitions (Annex A)
- Emma Codes (Annex B)
- Example of signal status (Annex C)
- Proposed digital interface sentences for Inland AIS (Annex D)
- ERI ship types (Annex E)
- Overview of information required by the user and the data fields, which are available in the defined Inland AIS messages (Annex F).

Future developments may lead to alternative vessel tracking and tracing systems which must still be compatible with maritime AIS.

#### 2.4 Current editions

The current editions of the Standards are published on the Internet at www.ccr-zkr.org.

#### 2.5 Type approval of Inland AIS devices

Inland AIS devices are checked by a Competent Authority (type test) and are registered by it. As long as these devices have already been granted a type approval for maritime AIS, the type test may be limited to the requirements of the Inland AIS Test Standard. The CCNR website (<u>www.ccr-zkr.org</u>) contains registers of the Competent Authorities, the approved devices and accredited specialist firms. There is presently one Competent Authority:

Wasser- und Schifffahrtsverwaltung des Bundes Fachstelle der WSV für Verkehrstechniken Am Berg 3, D-56070 Koblenz (www.fvt.wsv.de)

#### 3. RIS fields of interest covered

The table below provides an overview of which fields of interest can be covered by Inland AIS. Each field is subdivided into tasks. The users are defined for each task.

Service	Task	User
Navigation	Medium term: Looking minutes up to hours ahead, outside on- board radar range	Conning skipper
	Short term: Looking minutes ahead, in on-board radar range	Conning skipper
	Very short term: Looking up to one minute ahead	Conning skipper
Vessel Traffic Management	VTS	VTS operator, conning skipper
	Lock operation	Lock operator, conning skipper
	Lock planning	Lock operator, conning skipper, shipmaster, fleet manager
	Bridge operation	Bridge operator, conning skipper
	Bridge planning	Bridge operator, conning skipper, shipmaster, fleet manager

#### Table 1.1: Overview of services, tasks and users

Service	Task	User
Calamity abatement service		Operator in calamity centre, VTS operator, lock operator, bridge operator, conning skipper, shipmaster, Competent Authority
Transport management	Voyage planning	Shipmaster, freight broker, fleet manager, terminal operator, conning skipper, VTS operator, lock operator, bridge operator, RIS operator
	Transport logistics	Fleet manager, shipmaster, consignor, consignee, supply forwarder
	Port and terminal management	Terminal operator, shipmaster, consignor, port authority, Competent Authority
	Cargo and fleet management	Fleet manager, consignor, consignee, supply forwarder, freight broker, shipmaster
Enforcement	Cross-border	Customs, Competent Authority, shipmaster
	Traffic safety	Competent Authority, shipmaster (police authorities)
Waterway and port infrastructure charges		Competent Authority, shipmaster, fleet manager, waterway authority
Fairway information service	Meteorological Information	Conning skipper
	Signal status	Competent Authority, shipmaster, fleet manager
	Water levels	Competent Authority, shipmaster, fleet manager, conning skipper

# 4. Functioning of Inland AIS

Onboard AIS devices transmit the identity of the vessel, its position and other data at regular intervals. By receiving these transmissions, AIS shore stations or ships fitted with AIS can automatically recognise, identify and track vessels equipped with AIS on a suitable screen, such as an inland ECDIS display. AIS systems are meant to boost the safety of navigation by use from vessel-to-vessel alongside onshore Vessel Traffic Services (VTS) to trace and track vessels and to assist in calamity abatement.

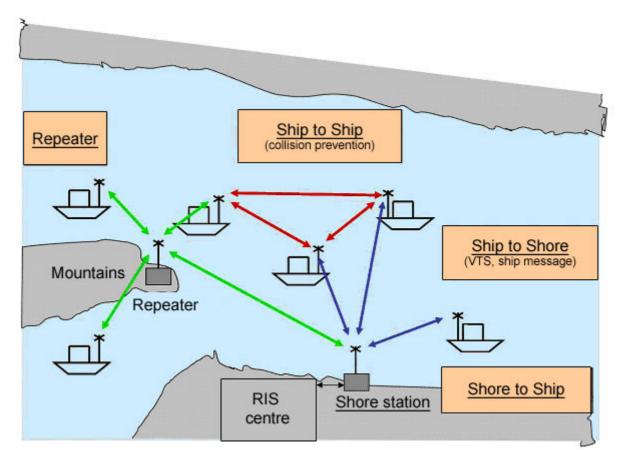


Illustration: Functioning of AIS

A peculiar trait of AIS is the autonomous mode which uses the SOTDMA (Self-Organised Time Division Multiple Access) procedure, thus dispensing with the need for a coordinating base station. The radio protocol is designed so that the ship stations work autonomously through exchanging access parameters for connection. The time is split into one-minute cycles with 2250 intervals per radio channel which are synchronised according to UTC time. Each participant organises their access to the radio channel by selecting free intervals, whilst taking account of the future use of intervals by other stations. There is no need for a central control point for assigning intervals.

# 5. Operating modes of AIS

The following operating modes can be distinguished for AIS

- a) Ship to ship: All vessels fitted with AIS are able to receive static and dynamic information from all other vessels equipped with AIS within the area of coverage.
- b) Ship to shore: Data from vessels equipped with AIS can also be picked up by AIS base stations and relayed to an RIS Centre where they can be used to display Tactical Traffic Information (TTI) and Strategic Traffic Information (STI).
- c) Shore to ship: Safety-related data can be transmitted to vessels by shore installations.

#### 6. AIS devices

An AIS device normally contains the following components:

- VHF transmitter/receiver (1 transmitter and 2 receivers),
- GNSS receiver,
- Data processor.

Various kinds of AIS device types or AIS stations may be distinguished:

- AIS mobile stations of Class A on all seagoing vessels subject to the requirements of the International Maritime Organisation (IMO) SOLAS Chapter V,
- AIS mobile stations of Class B CS/SO with restricted functionality, i.e. on seagoing leisure craft. If the local traffic regulations do permit, recreational vessels navigating in inland waterways may use AIS Class B "CS" stations as they do when navigating in maritime waters. AIS Class B stations installed on recreational vessels need to conform to the requirements defined in the international standard IEC 62287 (including DSC channel management),
- Inland AIS mobile stations, derivatives of AIS mobile stations of Class A with full Class A functionality at VDL level plus additional inland navigation functions,
- AIS base stations, including shore-based Simplex repeater stations,
- AIS nautical signal stations for use on signalling devices such as beacons and buoys. ("Aids to Navigation" AtoN).

AIS operates on the internationally defined VHF frequencies AIS 1 (161,975 MHz) and AIS 2 (162,025 MHz) and may be switched to other channels in the VHF maritime band.

#### 7. Information transmitted by Inland AIS

The information transmitted by Inland and maritime AIS is identical bar the data specific to inland navigation. The information transmitted by Inland AIS can be divided into the following categories:

- Static information, such as vessel number, call-sign, vessel name, vessel type,
- Dynamic information, such as position of the ship with data on accuracy and integrity status,

- Voyage-related information, such as length and beam of combinations, dangerous cargo,
- Information specific to inland navigation such as Standard European Vessel Number, type
  of combination, number of blue cones/lights as per ADN, estimated time of arrival (ETA) at
  locks, bridges, terminals, borders and presence of "blue signs",
- AIS has the capability for interaction by ship or shore personnel for short safety related text messaging.

For transmitting messages Inland AIS uses the same parameters and the same structure as AIS mobile stations of Class A, which the IMO prescribes for maritime navigation (IMO-AIS). Fields with unused parameters are defined as "not available". Elements marked with '\*' must be dealt with differently from seagoing vessels.

#### 7.1 Static ship information

Static or fixed information is already fed into the AIS device during installation onboard and need only be amended if, for example, the name of the vessel were to change.

Static ship information is broadcast automatically be the vessel or on request.

Identification characteristic of the radio (MMSI)	(as per IMO-AIS)
Ship name	(as per IMO-AIS)
Call sign	(as per IMO-AIS)
IMO number*	("not available" for inland navigation vessels)
Type of ship and cargo* <sup>#</sup>	(as per IMO-AIS/with extra data as per ERI)
Reference point for reported position (also reference point for dimension of ship / combination) <sup>#</sup>	(as per IMO-AIS)
Overall length of vessel or combination (dm)*#	(Inland AIS extension /data in dm)
Overall beam of vessel or combination (dm)*#	(Inland AIS extension /data in dm)
European Vessel Identification Number (ENI)	(Inland AIS extension)
Type of ship or combination (ERI)*#	(Inland AIS extension)

<sup>#</sup> Static data for ship; voyage related data for combination

#### 7.2 Dynamic ship information

Dynamic information, bar the navigation status, is automatically updated by the position sensor inside the AIS device or by the connected sensors.

Dynamic ship information is broadcast automatically from the vessel or on request.

Position (WGS 84)	(as per IMO-AIS)
Speed SOG*	(as per IMO-AIS/additional quality information)
Course COG*	(as per IMO-AIS/additional quality information)
Heading HDG*	(as per IMO-AIS/additional quality information)
Rate of turn ROT	(as per IMO-AIS)
Position accuracy and integrity information (GNSS/DGNSS)	(as per IMO-AIS)
Time of position-fixing	(as per IMO-AIS)
Navigation status	(as per IMO-AIS)
Blue sign set	(Inland AIS extension)
Quality of speed information	(Inland AIS extension,/derived from ship sensor or GNSS)
Quality of course information	(Inland AIS extension/derived from ship sensor or GNSS)
Quality of heading information	(Inland AIS extension,/derived from certified sensor (e.g. gyro)

#### 7.3 Voyage-related ship information

Voyage-related information is inputted manually and must be updated during the voyage where necessary.

Voyage-related ship information is broadcast automatically from the vessel or on request.

Destination (ERI location codes)	(as per IMO-AIS)
Category of dangerous cargo	(as per IMO-AIS)
Maximum present static draught *	(as per IMO-AIS with extension data in cm rather than dm)
ETA	(as per IMO-AIS)
Loaded/unloaded vessel <sup>+</sup>	(Inland AIS extension)
Hazardous cargo classification	(Inland AIS extension)

<sup>+</sup> Within the Standard Vessel Tracking and Tracing in Inland Navigation, Edition 1.01, this information is mentioned among the static ship information. However, it actually concerns dynamic ship information. See chapter 9 of this leaflet.

#### 7.4 Traffic management information

Traffic management information is for specific use in inland navigation. This information is transmitted when required or on request to/from inland vessels.

#### 7.5 ETA at lock/bridge/terminal

Information on ETA at lock/bridge/terminal is transmitted as an addressed message from ship to shore.

Lock/bridge/terminal ID (UN/LOCODE)	(Inland AIS extension)
ETA at lock/bridge/terminal	(Inland AIS extension)
Number of assisting tugboats	(Inland AIS extension)
Air draught (actual highest point of ship above water level)	(Inland AIS extension)

#### 7.6 RTA at lock/bridge/terminal

Information on RTA a lock/bridge/terminal is sent as an addressed message from shore to ship.

Lock/bridge/terminal ID (UN/LOCODE)	(Inland AIS extension)
RTA at lock/bridge/terminal	(Inland AIS extension)

#### 7.7 Number of persons on board

The number of persons on board is preferably to be transmitted as an addressed message from ship to shore, on request or when events dictate.

Total number of persons on board	(as per IMO-AIS)
Number of crew on board	(Inland AIS extension)
Number of passengers on board	(Inland AIS extension)
Number of shipboard personnel on board	(Inland AIS extension)

#### 7.8 Signal status

Information on Signal status is transmitted as a broadcast message from shore to ship.

Signal position (WGS 84)	(Inland AIS extension)
Signal form	(Inland AIS extension)
Signal status	(Inland AIS extension)

#### 7.9 EMMA weather warnings

EMMA weather warnings are transmitted as a broadcast message from shore to ship.

Local Weather warnings	(Inland AIS extension)
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#### 7.10 Water level reports

Water level reports are transmitted as a broadcast message from shore to ship.

Local water level information	(Inland AIS extension)
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#### 7.11 Safety-related messages

Safety-related messages are transmitted when required as broadcast messages to everyone or as addressed messages.

## 8. Reporting interval for information transmission

The different information types for Inland AIS are transmitted at different reporting intervals.

For ships travelling on inland waterways the reporting interval for dynamic data can be switched between the SOLAS mode (reporting interval for AIS mobile stations of Class A on maritime vessels) and the inland navigation mode.

The following reporting intervals apply:

Static ship information	Every 6 minutes or when data are amended or on request
Dynamic ship information	Depends on navigation status and operating mode of the ship, either in inland navigation or SOLAS mode (default setting), or on request. Ship "at anchor" every 3 minutes, Ship "en route" between 10 and 2 seconds
Voyage-related ship information	Every 6 minutes or when data are amended or on request
Traffic managementinformation	As required (in line with provisions of the Competent Authority)
Safety-related information	As required

When in inland navigation mode, the reporting interval for dynamic information may be reduced by up to 2 seconds in line with the provisions of the Competent Authority, via an AIS shore station or an onboard application.

Reporting interval for dynamic ship information:

Ship dynamic conditions	Nominal reporting interval
Ship status "at anchor" and speed not above 3 knots	3 minutes
Ship status "at anchor" and speed exceeding 3 knots	10 seconds
Ship with Inland AIS device with SOLAS reporting rate, speed 0 – 14 knots	10 Seconds
Ship with Inland AIS device with SOLAS reporting rate, speed 0 – 14 knots and changing course	3 1/3 seconds
Ship with Inland AIS device with SOLAS reporting rate, speed 14 – 23 knots	6 seconds
Ship with Inland AIS device with SOLAS reporting rate, speed 14 – 23 knots and changing course	2 seconds
Ship with Inland device with SOLAS reporting rate, speed exceeding 23 knots	2 seconds
Ship with Inland AIS device with SOLAS reporting rate, speed exceeding 23 knots and changing course	2 seconds
Ship with Inland AIS device with inland navigation reporting rate *	Assigned between 2 and 10 seconds

\* Can be assigned by the Competent Authority using AIS message 23 when the ship is in the inland waterway area.

# 9. On-board operation of Inland AIS devices

The Inland AIS device shall be in permanent operation whenever the ship is at anchor or en route. When in port, operation will take place in accordance with the regulations in force in the port in question.

The shipmaster shall manually input the following data at the start of the voyage and whenever the data are amended:

- Correct navigation status,
- Category of dangerous cargo (number of blue cones),
- Draught of the ship,
- Loaded/unloaded,
- Port of destination and ETA.

In addition to the data mentioned above following data have to be set in case of combinations:

- Type of combination,
- Length/beam of combination,
- Reference point for reported position (also reference point for dimension of ship / combination).

The conning skipper must check data to ensure that the static ship data are correct and reflect the latest situation. This must be done at least once a month. At certain intervals the shipmaster must also check the dynamic data of his own AIS device, such as position, course and speed.

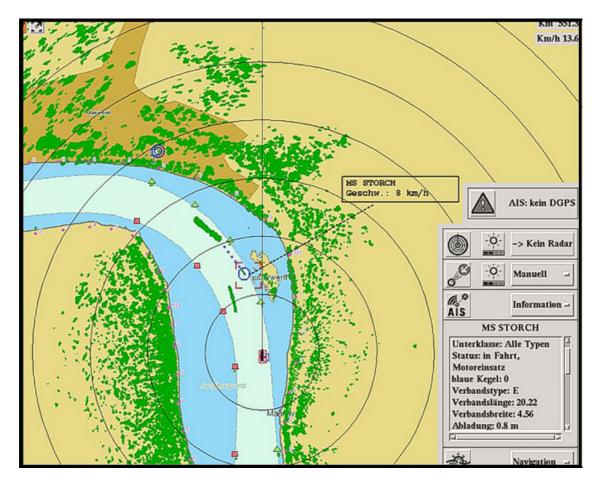
Once the Inland AIS device comes into operation it must perform an ongoing built-in integrity test (BIIT). If a functional anomaly occurs in the Inland AIS device an error message must be displayed and, if necessary, the Inland AIS device should cease broadcasting information.

## 10. Display of information transmitted by Inland AIS

The minimum keyboard and display (MKD) for Inland AIS devices serves to input voyage-related ship data and other vessel-specific data such as status indication and alarm messages.

The MKD may also show AIS messages received, such as ship name, distance and heading of the reporting ship, alphanumerically. Other ship data can be displayed by selecting a given ship.

This form of displaying AIS data is not suited for navigational support. When using AIS data onboard, it would appear that a graphical display like Inland ECDIS is essential.



<u>Illustration</u>: Display of the position of a vessel fitted with AIS (MS Storch) on an Inland ECDIS device in navigation mode as an omnidirectional symbol, showing the name of the vessel as a moving blip alongside the additional ship data table in a separate window.

## 11. Installation of Inland AIS devices on board

The proper installation is a prerequisite for the correct functioning of each Inland AIS device on board. Therefore the Tracking and Tracing Expert Group has developed Guidelines on the installation of the Inland Automatic Identification System (Inland AIS). These guidelines can be downloaded from the CCNR website (www.ccr-zkr.org). This document is meant as a guide for approved firms, installing Inland AIS stations on board of inland vessels. Its purpose is to guide the installation, configuration and testing of the equipment to ensure a correct setup.

This document is meant to be used in addition to the installation manuals of the manufacturer providing the Inland AIS station.

The following actions have to be taken during installation:

- Install the Inland AIS station on board, according to the installation manual provided by the manufacturer,
- Configure the Inland AIS station as per the installation manual,

- Carry out testing of the Inland AIS station for correct operation and settings,
- Document all settings in the "Report about installation and operation of the Inland AIS station",
- Train the skipper in editing the static and voyage related data as appropriate and how to handle alarm messages of the Inland AIS station,
- Hand over the "Report about installation and operation of the Inland AIS station" to the skipper / ship owner to keep it on board and to the installation firm for its records.

The relevant local regulations must be followed regarding documents to be kept on board and to be submitted to the national competent authority (e.g. CCNR-report about installation and operation of the Inland AIS station).

# 12. Status of Inland AIS implementation in European Countries

	Inland AIS	Geographical coverage of waterways of Class Va or higher		Landbased AIS infrastructure		
	Countries	dGPS via AIS	Water level via AIS	Equipment programme	Status 2011	Outlook 2012
AT	Austria					
BE	Flanders Brussels Wallonia					
BG	Bulgaria					
СН	Switzerland					
CZ	Czech Republic					
DE	Germany					
FR	Seine North Moselle-Rhine-Saône-Rhône Garonne					
HR	Croatia					
HU	Hungary					
LU	Luxembourg					
NL	Netherlands					
PL	Poland					
RO	Romania					
RS	Serbia					
SK	Slovakia					
UA	Ukraine					

Status:		
No Information		
No activities planned		
In preparation/realisation		
Is going on		
Completed		
Pilot operation		
Fully operational		

# 13. Contacts

European Expert Group "Vessel Tracking and Tracing on Inland Waterways"

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Email address:	VTT-secretariat@risexpertgroups.org

# 14. Abbreviations

i	· · · · · · · · · · · · · · · · · · ·
ADN	European Agreement concerning the International Carriage of Dangerous Goods by Inland Waterways
COG	Course Over Ground
CS	Carrier Sense
DGNSS	Differential GNSS
ECDIS	Electronic Chart Display and Information System
EMMA	European Multiservice Meteorological Awareness System
ERI	Electronic Reporting International
GNSS	Global Navigation Satellite System
HDG	Heading
ID	Identifier
LOCODE	Location Code
MMSI	Maritime Mobile Service Identifier
ROT	Rate Of Turn
RTA	Requested Time of Arrival
SOG	Speed Over Ground
SOLAS	Safety Of Life At Sea
UTC	Universal Time Coordinated
VDL	VHF Data Link
VHF	Very High Frequency
VTS	Vessel Traffic Services
WGS 84	World Geodatic System from 1984